

AniTMT Hackers guide I – Animation System

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1 Introduction

This Program is still in an early stage but we are pleased about any kind of feedback. We are very sorry about the few comments in the source yet.

For a reference to code files we only use the filename of the header file (`.hpp`) even if we also talk about the implementation (`.cpp`).

2 Program structure

The Mother of the object hierarchy is an object of the class `Animation` (`anitmt.hpp`). It contains an object for the global options, a list of script objects, a list of scenes and a list of files that only have to be copied. The global options may be defined as command line parameter or within ini files (`globals.hpp`). The virtual base class for script objects is declared in `script.hpp` and the derived class for adl scripts – the only animation description language already implemented – is situated in `adl.hpp`. The scene objects (`scene.hpp`) may contain a list of components that may contain a list of functions that may contain a list of subfunctions (`ani_base.hpp`). All these objects are derived from a class called `Linked_Valtree` that is again derived from `Valtree` (`valtree.hpp`). The `Valtree` class provides this tree behaviour where each node has a list of child `Valtrees` and a list of properties that have a name a general value type for scalars, vectors or strings (`vals.hpp`). With the aid of a list of property solvers each `Valtree` provides the method `solve_property(name)` to solve for one property. Each `Linked_Valtree` node within this object hierarchy additionally knows his previous and next defined node. This is used by functions that solve properties with the help of neighbour `Linked_Valtrees` (see chapter 4).

All functions with its subfunctions are derived from the classes defined in `ani_base.cpp`. One example is the move function for objects (`object.hpp`). The general subfunction

class `Subfunc_Move_object` provides the functions to make it possible to solve for the properties that are common for all track elements. In order to calculate the resulting position it declares some pure virtual functions that have to be implemented by each specialized track like a straight element (`straight.hpp`) or a circle (`circle.hpp`). These files are very important to improve AniTMT. Each child type has to be inserted in one function of the parent. To add a new function you have to insert it into `Component::get_function()` in `ani_base.cpp`. If you want to add a new track type for the move function you have to add it in `Move_Object::get_subfunction()` in `object.cpp`. Then you may copy the source for the straight track element and modify it. If you would like to add property solver for a continuously accelerated system you may use the `add_accelerated_solver()` function.

Finally the results of each Component has to be written into files. This is scene type and component type dependant. That is why each scene provides scene adapters for each component type (scalar, vector or object). These adapters provide component type specific interfaces to set the result and scene specific parts that detect components in the scene description files and write the result in the correct file.

3 Sequence of Execution

The program starts in `main.cpp`. It only creates an object of the main Animation class (`anitmt.hpp`) and calls the start method with the command line parameters as argument. This function orders to interpret the arguments, to read the files, to solve the animation, to write down the results and to copy the needed files.

At first all scripts and non moving scenes defined by command line parameters or ini files are added. Afterwards the program reads the script files and adds more scenes with the whole object tree of included components, functions and subfunctions. Then there go some function calls through the whole object tree to solve for undefined properties (see chapter 4). Another function call follows for each frame to calculate the non-moving scenes and write them to files. Afterwards all other files needed for the rendering process are copied to the animation directory.

4 The AniTMT Solve System

`Valtree` is the base class of all elements in the main object hierarchy. It provides a mechanism to solve for any property of an element. Therefore property solver may be added that know all the possibilities to solve for a specific property. The solvers are stored in a `std::multimap` called `Valtree::property_solve`. During the solve process a `map` of `search_infos` stores which properties are locked because they are already in the search path and wheather the property has to try to solve itself again. Therefore it stores an id that is increased everytime a property is solved. If the id didn't change since the last trial a property doesn't try to solve itself again. You can find some simple property solvers in `scalar.cpp`. They all start with `SCA_Solve_\dots`.

In the object tree of the scenes every element is even derived from `Linked_Valtree`. This class provides a solve system that isn't limited to one element. This is for example very useful for animation functions with concatenated tracks. Two attached track elements should have the same time and position between them. Moreover it could be useful to have the same direction or even speed. The `Linked_Valtree` provides therefore a solve system that works on different priorities. On each priority level an element may pass some properties to its neighbours which will take it if they couldn't solve for the corresponding property. The `set_priority()` function increases the number of priority levels if necessary. Each element that wants to take part in this communication has to overload the virtual function `send_command()`. You can find an interesting one in `object.cpp` but the basics may also be seen in `scalar.cpp`.

Additionally `Linked_Valtrees` provide functions to set properties by default. This is also done in different levels. To make use of this an element needs an implementation of `allow_default()`. The most interesting one should also be in `object.cpp`.

The function that controls all these priority levels is called `Animation::solve()` and resides in `anitmt.cpp`.

Finally the function `Animation::calc()` in `anitmt.cpp` starts the execution of `calc_res()` of all elements that has to calculate the final positions and values for each frame. In `scalar.cpp` you can find an implementation of `Linear_Change_Scalar::calc_res()` that calculates a linear interpolation. In `object.cpp` is a very general implementation `Subfunc_Move_Object::calc_res()` that provides a track independent calculation of accelerated movement and rotation so that all concrete track types only have to implement some special functions to get the real position and directions. There is a short implementation of the five functions `get_pos()`, `get_front()`, `get_up()`, `get_end_up()` and `get_first_up` (default up) in `staight.cpp`.

5 File Reference

The following tables give a brief information about all Objects of `anitmt-calc`. The corresponding file with the `.hpp` extension is the declaration and the file with the `.cpp` extension is implementation.

Files of AniTMT:

Object without extension	Description
main	main() function that only calls <code>Animation::start()</code>
anitmt	Main object <code>Animation</code> with initial calls
globals	Class for global animation options defined by the user
copy	Class for files that only have to be copied
script	Base class that handles animation script files
adl	Derived Class that handles <code>adl</code> scripts
valtree	This class is used for nodes in a object hierarchy where every node owns a list of child nodes and a list of properties
scene	Base class that handles source scenes; all scenes are the root of a <code>valtree</code> object hierarchy
povscene	Derived Class that handles POV-Ray scenes
ani_base	Basic object hierarchy within a scene (<code>Component</code> , <code>Function</code> , <code>Subfunction</code>)
scalar	Scalar functions (<code>change { linear and accelerated }</code>)
object	Object functions (only move at the moment) and the basic subfunction that provides track independant accelerated movement and rotation
straight	Subfunction for move for straight track elements
circle	Circular track elements for move
accel	This is very useful for subfunctions to provide accelerated systems like: <code>length</code> , <code>startspeed</code> , <code>endspeed</code> , <code>acceleration</code> and <code>duration</code>
utils	Templates to delete all elements of lists or maps
p_aninfo	Parser info to provide access from expressions to values of the internal animation structure like references to other expressions

Independant Utilities of AniTMT with an expression Parser:

Object without extension	Description
<code>error</code>	My basic error class with or without position information
<code>vals</code>	Basetype values::Valtype that can be one of scalar, vector or string and may be calculated with all common operators.
<code>mystream</code>	Character and word streams (Tokenstreams)
<code>parser</code>	Provides a Parser that can read any expressions with scalars, vectors and strings in any word stream
<code>parsinfo</code>	Some basic parser infos that may be inserted in parser objects to provide constants or functions like <code>sin</code> , etc...
<code>files</code>	File classes for word streams and precompiled files with <code>#include</code> directives that may be changed while copying
<code>constant</code>	Konstants like π and e
<code>vector3</code>	Vector library of Roberto Javier Peon (LGPL)
<code>vector</code>	Puts the vector library into namespace <code>vect</code>
<code>matrix</code>	Basic matrix library especially for rotations
<code>ini</code>	Read and write functions for ini files with sections and options